

The Heisenberg group and $SL_2(\mathbb{R})$

a survival pack

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Phase space, quantum blobs

and squeezed coherent states

- ▶ *Quantum blobs*¹ are the smallest phase space units of phase space compatible with the uncertainty principle of quantum mechanics;
- ▶ Quantum blobs are in a bijective correspondence with the *squeezed coherent states*² from standard quantum mechanics, of which they are a phase space picture;
- ▶ Quantum blobs have the *symplectic group* as group of symmetries;
- ▶ Thus: blobs (aka squeezed states) are a family invariant under quadratic Hamiltonians, which transform them *geometrically*, that is by a change of variables.

Question: Do we have other states transformed geometrically by quadratic Hamiltonians?

Answer (well-known, yet will be revised): For the harmonic oscillator any state is moving geometrically in the phase space.

¹M. A. d. Gosson, “Quantum Blobs”, 2013.

²Gazeau, *Coherent States in Quantum Physics*, 2009; M. d. Gosson, *Symplectic Geometry and Quantum Mechanics*, 2006.

Ladder Operators

and the Hermite functions

Let P and Q satisfy CCR: $[Q, P] = i\hbar I$ of the Weyl algebra \mathfrak{h}_1 . Consider complexification of \mathfrak{h}_1 and define operators:

$$a^\pm = \sqrt{\frac{m\omega}{2\hbar}} \left(Q \mp \frac{i}{m\omega} P \right), \quad \text{then} \quad [a^-, a^+] = 1. \quad (1)$$

For a solution $|0\rangle$ of $a^- |0\rangle = 0$ we define $|n\rangle = (\pi^n n!)^{-1/2} (a^+)^n |0\rangle$, then:

1. $(a^-)^* = a^+$ on $L_2(\mathbb{R})$.
2. The name *ladder* operators is explained by the diagram:

$$|0\rangle \begin{array}{c} \xrightarrow{a^+} \\ \xleftarrow{a^-} \end{array} |1\rangle \begin{array}{c} \xrightarrow{a^+} \\ \xleftarrow{a^-} \end{array} |2\rangle \begin{array}{c} \xrightarrow{a^+} \\ \xleftarrow{a^-} \end{array} |3\rangle \begin{array}{c} \xrightarrow{a^+} \\ \xleftarrow{a^-} \end{array} \dots$$

Since

$$(a^-) |n\rangle = -(\pi n)^{1/2} |n-1\rangle, \quad (a^+) |n\rangle = (\pi(n+1))^{1/2} |n+1\rangle$$

3. Orthonormality: $\langle n|k\rangle = \delta_{nk}$.

Ladder Operators

and representation theory

The above construction relies on CCR: $[Q, P] = i\hbar I$ or $[a^-, a^+] = 1$ only.

No specific realisation is assumed. Conclusions:

- ▶ There are different vacuums $|0\rangle$ (that is $a^- |0\rangle = 0$) for different $m\omega$.
- ▶ Any normalised vacuum $|0\rangle$ creates the orthonormal basis $\{|n\rangle\}_n$ of an irreducible invariant space.
- ▶ Any two irreducible spaces are isomorphic by $|n\rangle \rightarrow |n\rangle'$.
- ▶ Thus, it provides the (constructive!) proof of the Stone-von Neumann theorem on the uniqueness of representation of CCG.

Remark 1.

- ▶ There is no genuinely “non-squeezed” states, they are all squeezed in a different way.
- ▶ All vacuums are minimising uncertainty $\Delta Q \cdot \Delta P (\geq \frac{\hbar}{2})$.
- ▶ Obviously, this approach inspired Bargmann to produce classification of UIRs of $SL_2(\mathbb{R})$.

Ladder Operators

and quantum harmonic oscillator

Hamiltonian of the harmonic oscillator.

$$H = \frac{\hbar\omega}{2}(a^+ a^- + a^- a^+) = \hbar\omega(a^+ a^- + \frac{1}{2}) = \frac{1}{2m}P^2 + \frac{m\omega^2}{2}Q^2. \quad (2)$$

Using identities in 2 we obtain spectral decomposition

$$H |n\rangle = \hbar\omega(n + \frac{1}{2}) |n\rangle.$$

1. The spectrum of the harmonic oscillator is discrete.
2. The eigenfunctions are provided by the $|n\rangle$.
3. The ladder operators acts on the spectrum by a shift $\hbar\omega$ due to the commutation relation $[H, a^\pm] = 2a^\pm$:

$$\begin{aligned} H(a^+ |k\rangle) &= (a^+ H + 2a^+) |k\rangle = a^+(H|k\rangle) + 2a^+ |k\rangle \\ &= (2k + 1)a^+ |k\rangle + 2a^+ |k\rangle = (2k + 3)a^+ |k\rangle. \end{aligned}$$

Hamiltonian from Ladder Operators

pros and contras

- ▶ Representation independent.
- ▶ Inspired ladder technique for other Hamiltonians, e.g. hydrogen atom by Schrödinger or recent works in SUSY QM.
- ▶ Time evolution of an arbitrary superposition $\sum a_n |n\rangle$ is $\sum e^{-i\omega(n+1/2)t} a_n |n\rangle$.
- ▶ In configuration space (the Schrödinger model) the dynamic is a Gauss-type (quadratic Fourier) integral transform.
- ▶ There is a specific space—Fock–Segal–Bargmann (FSB) space—which makes the dynamic geometric.

Harmonic oscillator

in FSB representation

Using the displacement operator $D(z) = e^{(\bar{z}a^+ + za^-)/2} = e^{xQ + yP}$, $z = m\omega x + iy$ (the representation of the Heisenberg group, in fact) we create the coherent states $|z\rangle = D(z)|0\rangle$ and the coherent state transform:

$$\mathcal{W} : f \mapsto f(z) = \langle f|z\rangle \quad (3)$$

The image—the Fock–Segal–Bargmann space—consists of analytic functions on \mathbb{C} . Hamiltonian of the harmonic oscillator:

$$\begin{aligned} H &= \frac{1}{2m} (d\tilde{\sigma}_h^x)^2 + \frac{m\omega^2}{2} (d\tilde{\sigma}_h^y)^2 \\ &= \frac{1}{2m} \partial_{xx}^2 + \frac{m\omega^2}{2} \partial_{yy}^2 \\ &\quad + i\pi\hbar \left(m\omega^2 x \partial_y - \frac{1}{m} y \partial_x \right) - \pi^2 \hbar^2 \left(\frac{m\omega^2}{2} x^2 + \frac{1}{2m} y^2 \right). \end{aligned} \quad (4)$$

The oscillator's dynamics in FSB space is geometric rotation:

$$A_t : f(z) \mapsto e^{-\pi\hbar(i\omega t - m\omega y^2 - x^2/(m\omega))} f(e^{-2\pi i\hbar\omega t} z)$$

despite of the presence of the second derivatives!

Harmonic oscillator

a solution in FSB space

*The mystery resolved:*³

Functions in FSB transform are analytic functions of the variable $z = m\omega x + iy$, thus the second order “Laplacian”

$$\frac{1}{2m}\partial_{xx}^2 + \frac{m\omega^2}{2}\partial_{yy}^2$$

vanishes on FSB space.

The key element:

the representation on the phase space is reducible, giving the room for an additional condition(s), e.g. analyticity, to specify vectors from the irreducible component.

Question: Are there other examples of a geometric dynamic?

³Almalki and Kisil, “Geometric Dynamics of a Harmonic Oscillator, Non-Admissible Mother Wavelets and Squeezed States”, 2018.

The shear Lie algebra

just one nilpotency step away from the Heisenberg–Weyl

Let \mathfrak{a} be the three-step nilpotent Lie algebra whose basic elements $\{X_1, X_2, X_3, X_4\}$ with the following non-vanishing commutators^{4,5}

$$[X_1, X_2] = X_3, \quad [X_1, X_3] = X_4. \quad (5)$$

Obviously, $\{X_1, X_3, X_4\}$ is the Heisenberg–Weyl algebra. We will systematically employ this inclusion to save our calculations.

The algebra \mathfrak{a} and respective Lie group—the *shear group* (aka *quartic group*⁶ or *Engel group*⁷)—is a toy model to try any generalisations^{8,9}.

⁴Corwin and Greenleaf, *Representations of Nilpotent Lie Groups and Their Applications. Part I*, 1990.

⁵Kirillov, *Lectures on the Orbit Method*, 2004.

⁶Klink, “Nilpotent Groups and Anharmonic Oscillators”, 1994.

⁷Ardentov and Sachkov, “Maxwell Strata and Cut Locus in the Sub-Riemannian Problem on the Engel Group”, 2017.

⁸Howe, Ratcliff, and Wildberger, “Symbol Mappings for Certain Nilpotent Groups”, 1984.

⁹I. Beltiță, D. Beltiță, and Pascu, “Boundedness for Pseudo-Differential Calculus on Nilpotent Lie Groups”, 2013.

The shear group

including the Heisenberg group

The corresponding Lie group is a three-step nilpotent \mathbb{A} and the group law is given by:

$$(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4)(\mathbf{y}_1, \mathbf{y}_2, \mathbf{y}_3, \mathbf{y}_4) = (\mathbf{x}_1 + \mathbf{y}_1, \mathbf{x}_2 + \mathbf{y}_2, \mathbf{x}_3 + \mathbf{y}_3 + \mathbf{x}_1\mathbf{y}_2, \quad (6) \\ \mathbf{x}_4 + \mathbf{y}_4 + \mathbf{x}_1\mathbf{y}_3 + \frac{1}{2}\mathbf{x}_1^2\mathbf{y}_2),$$

where $\mathbf{x}_j, \mathbf{y}_j \in \mathbb{R}$ and the *canonical coordinates* are

$(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4) := \exp(\mathbf{x}_4\mathbf{X}_4) \exp(\mathbf{x}_3\mathbf{X}_3) \exp(\mathbf{x}_2\mathbf{X}_2) \exp(\mathbf{x}_1\mathbf{X}_1)$. The identity element is $(0, 0, 0, 0)$ and the inverse of an element $(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4)$ is

$$(-\mathbf{x}_1, -\mathbf{x}_2, \mathbf{x}_1\mathbf{x}_2 - \mathbf{x}_3, \mathbf{x}_1\mathbf{x}_3 - \frac{1}{2}\mathbf{x}_1^2\mathbf{x}_2 - \mathbf{x}_4).$$

The group centre is

$$\mathbf{Z}(\mathbb{A}) = \{(0, 0, 0, \mathbf{x}_4) \in \mathbb{A} : \mathbf{x}_4 \in \mathbb{R}\}.$$

The Heisenberg group \mathbb{H} is isomorphic to the subgroup

$\tilde{\mathbb{H}} = \{(\mathbf{x}_1, 0, \mathbf{x}_3, \mathbf{x}_4) \in \mathbb{A} : \mathbf{x}_j \in \mathbb{R}\}$ by $(\mathbf{x}, \mathbf{y}, s) \mapsto (\mathbf{x}, 0, \mathbf{y}, s)$, $(\mathbf{x}, \mathbf{y}, s) \in \mathbb{H}$.

The shear group and Schrödinger group

The Schrödinger group is the semi-direct product $\mathbb{S} = \mathbb{H} \rtimes_{\mathbb{A}} \mathrm{SL}_2(\mathbb{R})$, where $\mathrm{SL}_2(\mathbb{R})$ is the group of all 2×2 real matrices with the unit determinant. The action \mathbb{A} of $\mathrm{SL}_2(\mathbb{R})$ on \mathbb{H} is given by:¹⁰

$$\mathbb{A}(g) : (x, y, s) \mapsto (ax + by, cx + dy, s), \quad (8)$$


where $g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \mathrm{SL}_2(\mathbb{R})$ and $(x, y, s) \in \mathbb{H}$. Let

$$\mathbb{N} = \left\{ \begin{pmatrix} 1 & 0 \\ x & 1 \end{pmatrix}, x \in \mathbb{R} \right\}$$

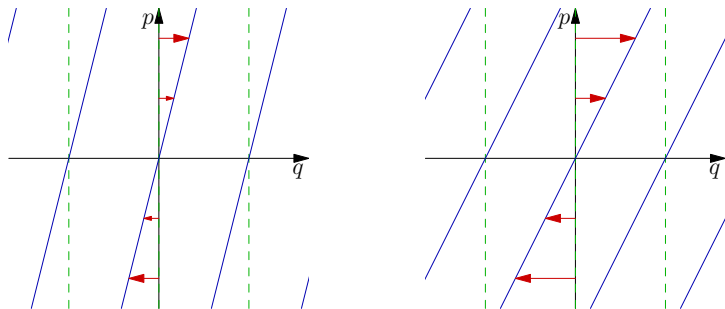
be the subgroup of $\mathrm{SL}_2(\mathbb{R})$, it is easy to check that \mathbb{A} is isomorphic to the subgroup $\mathbb{H} \rtimes_{\mathbb{A}} \mathbb{N}$ of \mathbb{S} through the map:

$$(x_1, x_2, x_3, x_4) \mapsto ((x_1, x_3, x_4), \mathfrak{n}(x_2)) \in \mathbb{H} \rtimes_{\mathbb{A}} \mathbb{N},$$

where $(x_1, x_3, x_4) \in \mathbb{H}$ and $\mathfrak{n}(x_2) := \begin{pmatrix} 1 & 0 \\ -x_2 & 1 \end{pmatrix} \in \mathrm{SL}_2(\mathbb{R})$.

¹⁰M. A. d. Gosson, *Symplectic Methods in Harmonic Analysis and in Mathematical Physics*, 2011; Folland, *Harmonic Analysis in Phase Space*, 1989. 

The shear group and Schrödinger group



Geometrically: *shear transform* with the angle $\tan^{-1} \alpha_2$:

$$n(\alpha_2)(\alpha_1, \alpha_3) := \begin{pmatrix} 1 & 0 \\ -\alpha_2 & 1 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_3 \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ -\alpha_2 \alpha_1 + \alpha_3 \end{pmatrix}. \quad (9)$$

Physically, for a particle with coordinate α_3 and the constant velocity α_1 : after a period of time $-\alpha_2$ the particle will still have the velocity α_1 but its new coordinate will be $\alpha_3 - \alpha_2 \alpha_1$.

UIR of the shear group

induction and the Kirillov's orbit method

Classification of UIRs of the shear group is nicely accomplished by the Kirillov's orbit method (by Kirillov himself¹¹ :-) and UIRs are explicitly constructed by the Mackey induction procedure.

Avoiding details, the main set of UIRs is parametrised by two "Planck constants" \hbar_2 and \hbar_4 and induced by the character

$\chi_{\hbar_2 \hbar_4}(0, x_2, x_3, x_4) = e^{2\pi i(\hbar_2 x_2 + \hbar_4 x_4)}$ of the maximal abelian subgroup $H_a = \{(0, x_2, x_3, x_4)\}$ in $L_2(\mathbb{R})$ is:¹²

$$[\rho_{\hbar_2 \hbar_4}(x_1, x_2, x_3, x_4)f](x'_1) = e^{2\pi i(\hbar_2 x_2 + \hbar_4(x_4 - x_3 x'_1 + \frac{1}{2} x_2 x_1'^2))} f(x'_1 - x_1). \quad (10)$$

This representation is irreducible since its restriction to the Heisenberg group \mathbb{H} coincides with the irreducible Schrödinger representation with \hbar_4 being the Planck constant.

¹¹Kirillov, *Lectures on the Orbit Method*, 2004, § 3.2.

¹²Ibid., 2004, § 3.3, (19).

Coherent state transform

aka voice transform, wavelet transform, etc.

For a G , ρ and a fixed *mother wavelet* $\phi \in H$, the wavelet transform¹³ is:

$$[\mathcal{W}_\phi^\rho f](g) = \langle \rho(g^{-1})f, \phi \rangle = \langle f, \rho(g)\phi \rangle, \quad g \in G.$$

Let a mother wavelet ϕ be a joint eigenvector of $\rho(h)$ for all $h \in H$:

$$\rho(h)\phi = \chi(h)\phi \quad \text{for all } h \in H. \quad (11)$$


and a character χ of H . Then

$$[\mathcal{W}_\phi^\rho f](gh) = \bar{\chi}(h)[\mathcal{W}_\phi^\rho f](g). \quad (12)$$

Thus the restriction of the left regular representation Λ (intertwined with ρ by \mathcal{W}_ϕ^ρ) is induced by χ . For a section $s: G/H \rightarrow G$, and ϕ satisfying (11), *induced wavelet transform*¹⁴ \mathcal{W}_ϕ^ρ is

$$[\mathcal{W}_\phi^\rho f](x) = \langle f, \rho(s(x))\phi \rangle, \quad x \in G/H. \quad (13)$$

¹³Ali, Antoine, and Gazeau, *Coherent states, wavelets, and their generalizations*, 2014.

¹⁴Kisil, “Erlangen Programme at Large: an Overview”, 2012; Kisil, “Symmetry, Geometry, and Quantization with Hypercomplex Numbers”, 2017. 



Coherent state transform

for the shear group

For $H = \{(0, 0, 0, x_4) \in \mathbb{A} : x_4 \in \mathbb{R}\}$ and the character

$\chi(0, 0, 0, x_4) = e^{2\pi i \hbar_4 x_4}$ any function $\phi \in L_2(\mathbb{R})$ satisfies the eigenvector property (11). Thus, for the respective homogeneous space $\mathbb{A}/Z \sim \mathbb{R}^3$ and the section $s : \mathbb{A}/Z \rightarrow \mathbb{A}$; $s(x_1, x_2, x_3) = (x_1, x_2, x_3, 0)$ the induced wavelet transform is:

$$\begin{aligned} [\mathcal{W}_\phi f](x_1, x_2, x_3) &= \langle f, \rho_{\hbar_2 \hbar_4}(s(x_1, x_2, x_3))\phi \rangle & (14) \\ &= \int_{\mathbb{R}} f(y) e^{-2\pi i (\hbar_2 x_2 + \hbar_4 (-x_3 y + \frac{1}{2} x_2 y^2))} \overline{\phi}(y - x_1) dy \\ &= e^{-2\pi i \hbar_2 x_2} \int_{\mathbb{R}} f(y) e^{-2\pi i \hbar_4 (-x_3 y + \frac{1}{2} x_2 y^2)} \overline{\phi}(y - x_1) dy. \end{aligned}$$

For the Heisenberg group ($x_2 = 0$) it is Fourier–Wigner transform.¹⁵

For the share group it is the *quadratic Fourier transform* or the *Gauss integral transform*.¹⁶

¹⁵Folland, *Harmonic Analysis in Phase Space*, 1989.

¹⁶Neretin, *Lectures on Gaussian Integral Operators and Classical Groups*, 2011;

M. A. d. Gosson, *Symplectic Methods in Harmonic Analysis and in Mathematical Physics*, 2011.



CST on the shear group

non-square-integrability, is it an issue?

For a fixed unit vector $\phi \in L_2(\mathbb{R})$, let $L_\phi(\mathbb{A}/\mathbb{Z})$ be the image space of the wavelet transform \mathcal{W}_ϕ (14) equipped with the family of inner products parametrised by $x_2 \in \mathbb{R}$

$$\langle u, v \rangle_{x_2} := \int_{\mathbb{R}^2} u(x_1, x_2, x_3) \overline{v(x_1, x_2, x_3)} \mathfrak{h}_4 dx_1 dx_3. \quad (15)$$

The respective norm is denoted by $\|u\|_{x_2}$.

\mathcal{W}_ϕ is unitary map $H \rightarrow L_\phi(\mathbb{A}/\mathbb{Z})$, $\|\cdot\|_{x_2}$, furthermore we have the *orthogonality relation*:

$$\langle \mathcal{W}_{\phi_1} f_1, \mathcal{W}_{\phi_2} f_2 \rangle_{x_2} = \langle f_1, f_2 \rangle \overline{\langle \phi_1, \phi_2 \rangle} \quad \text{for any } x_2 \in \mathbb{R}. \quad (16)$$

Then its adjoint:

$$[\mathcal{M}_\phi(x_2)f](t) = \int_{\mathbb{R}^2} f(x_1, x_2, x_3) \rho(x_1, x_2, x_3, 0) \phi(t) \mathfrak{h}_4 dx_1 dx_3. \quad (17)$$

is its inverse: $\mathcal{M}_\psi(x_2) \circ \mathcal{W}_\phi = \langle \psi, \phi \rangle I$ if $\langle \psi, \phi \rangle = 1$.

Characterisation of CST image

and Lie derivatives

For the right shift $R(g) : f(g') \mapsto f(g'g)$, the covariant transform intertwines $R(g)$ with the action ρ on vacuum states:

$$R(g) \circ \mathcal{W}_\phi = \mathcal{W}_{\rho(g)\phi}. \quad (\text{cf. } \Lambda(g) \circ \mathcal{W}_\phi = \mathcal{W}_\phi \circ \rho(g)). \quad (18)$$

Let ρ be a UIR of G , which can be extended¹⁷ by integration to a vector space V of functions or distributions on G . If $\phi \in H$ satisfy the

$$\rho(a)\phi = 0, \quad \text{where } \rho(a)\phi = \int_G a(g) \rho(g)\phi dg = 0,$$

for a fixed distribution $a(g) \in V$. Then any wavelet transform $\tilde{v}(g) = \langle v, \rho(g)\phi \rangle$ obeys the condition:¹⁸

$$R(\bar{a})v = 0, \quad \text{where } R(\bar{a}) = \int_G \bar{a}(g) R(g) dg, \quad (19)$$

with R being the right regular representation of G .

¹⁷Feichtinger and Gröchenig, “Banach spaces related to integrable group representations and their atomic decompositions. I”, 1989.

¹⁸Kisil, “Erlangen Programme at Large: an Overview”, 2012; Kisil, “The Real and Complex Techniques in Harmonic Analysis from the Point of View of Covariant Transform”, 2014.

The shear group CST

image characterisation: structural condition

The derived representations of the basis $\{X_1, X_2, X_3, X_4\}$ of \mathfrak{a} are:

$$d\rho_{\hbar_2\hbar_4}^{X_1} = -\frac{d}{dy}; \quad d\rho_{\hbar_2\hbar_4}^{X_2} = 2\pi i\hbar_2 + \pi i\hbar_4 y^2; \quad d\rho_{\hbar_2\hbar_4}^{X_3} = -2\pi i\hbar_4 y; \quad (20)$$

Lie derivative \mathfrak{L}^X is the derived right regular representation:

$$\mathfrak{L}^{X_1} = \partial_1; \quad \mathfrak{L}^{X_2} = \partial_2 + x_1\partial_3 - i\pi\hbar_4 x_1^2 I; \quad \mathfrak{L}^{X_3} = \partial_3 - 2\pi i\hbar_4 x_1 I; \quad (21)$$

Any function ϕ satisfies the relation for the derived representation

$$\left((d\rho_{\hbar_2\hbar_4}^{X_3})^2 - 4\pi i\hbar_4 d\rho_{\hbar_2\hbar_4}^{X_2} - 8\pi^2\hbar_2\hbar_4 I \right) \phi = 0.$$

The image $f \in L_\phi(\mathbb{A}/\mathbb{Z})$ of the wavelet transform \mathcal{W}_ϕ is annihilated by the respective Lie derivatives operator $\mathcal{S}f = 0$ where

$$\begin{aligned} \mathcal{S} &= (\mathfrak{L}^{X_3})^2 + 4\pi i\hbar_4 \mathfrak{L}^{X_2} - 8\pi^2\hbar_2\hbar_4 I \\ &= \partial_{33}^2 + 4\pi i\hbar_4 \partial_2 - 8\pi^2\hbar_2\hbar_4 I. \end{aligned} \quad (22)$$

This will be called the *structural condition* because it is determined by the structure of the particular representation $\rho_{\hbar_2\hbar_4}$ (10).



The shear group CST

image characterisation: the Gaussian

A particular choice of a mother wavelet ϕ such that ϕ lies in $L_2(\mathbb{R})$ and is a null solution to the “first order” operator, cf. (20):

$$d\rho_{\hbar_2\hbar_4}^{X_1+\alpha X_2+iEX_3} = d\rho_{\hbar_2\hbar_4}^{X_1} + \alpha d\rho_{\hbar_2\hbar_4}^{X_2} + iE d\rho_{\hbar_2\hbar_4}^{X_3}, \quad (23)$$

where α and E some real constants. It is clear that, the function

$$\phi(y) = \exp\left(\frac{\pi i \alpha \hbar_4}{3} y^3 + \pi E \hbar_4 y^2 + 2\pi i \alpha \hbar_2 y\right),$$

is a generic solution and square integrability of ϕ requires that $E\hbar_4$ is strictly negative. Furthermore, for the purpose of this work it is sufficient to use the simpler mother wavelet corresponding to the value $\alpha = 0$:

$$\phi(y) = e^{\pi E \hbar_4 y^2}, \quad \hbar_4 > 0, E < 0. \quad (24)$$

If $\alpha \neq 0$ then we obtain Airy beam decomposition (cubic Fourier transform).¹⁹

¹⁹Torre, “A Note on the Airy Beams in the Light of the Symmetry Algebra Based Approach”, 2009.

The shear group CST

image characterisation: the analytic condition

Any function f in $L_\phi(\mathbb{A}/\mathbb{Z})$ for ϕ (24) satisfies $\mathcal{C}f = 0$ for the partial differential operator produced from (23) with $\mathbf{a} = 0$:

$$\mathcal{C} = (\mathcal{L}^{x_1} - iE\mathcal{L}^{x_3}) = \partial_1 - iE\partial_3 - 2\pi\hbar_4 E x_1. \quad (25)$$

By *peeling* (multiplication with a suitable factor) it can be converted into the Cauchy–Riemann equation, we call (25) the *analyticity condition*. The CST (14) with the Gaussian for the Haisenberg group ($\mathbf{x}_2 = 0$) becomes the Fock–Segal–Bargmann transform to analytic function of $z = -Ex_1 + ix_3$.

Since the structural operator $\mathcal{S} = \partial_{33}^2 + 4\pi i\hbar_4 \partial_2 - 8\pi^2 \hbar_2 \hbar_4 I$ (22) is a Schrödinger equation of a free particle (with \mathbf{x}_2 being time) we get

Physical characterisation of $L_\phi(\mathbb{A}/\mathbb{Z})$: consists of wavefunctions expanded from the phase space \mathbb{R}^2 to $\mathbb{R}^2 \times \mathbb{R}$ by free time-evolution.

Geometric dynamics of HO

from the Heisenberg group

The harmonic oscillator with mass m and frequency ω is quantised

$$\begin{aligned} H &= \frac{1}{2m} (\text{id}\tilde{\sigma}_h^{X_1})^2 + \frac{m\omega^2}{2} (\text{id}\tilde{\sigma}_h^{X_3})^2 \\ &= -\frac{1}{2m} \partial_{11}^2 - \frac{m\omega^2}{2} \partial_{22}^2 + \frac{2\pi i \hbar}{m} x_3 \partial_1 + \frac{2\pi^2 \hbar^2}{m} x_3^2 \end{aligned} \quad (26)$$

Our aim is dynamics in geometric terms by lowering the order of the differential operator (26) using the analyticity condition:

$$\tilde{H} = H + (A\partial_1 + iB\partial_3 + CI)(\mathcal{L}^{X_1} - iE\mathcal{L}^{X_3})$$

This requires $A = \frac{1}{2m}$, $B = -\frac{1}{2}\omega$, $C = -\pi\hbar\omega x_1$ and $E = -m\omega$.

$$\tilde{H} = \frac{2\pi i \hbar}{m} x_3 \partial_1 - 2\pi i \hbar m \omega^2 x_1 \partial_3 + \left(\pi \hbar \omega + \frac{2\pi^2 \hbar^2}{m} (x_3^2 - m^2 \omega^2 x_1^2) \right) I. \quad (27)$$

The solution is given by the rotation of the complex variable $x_3 - im\omega x_1$.

New observation: the value of E is uniquely defined and the

corresponding vacuum vector $\phi(q) = e^{\pi\hbar E q^2} = e^{-\pi\hbar m \omega q^2}$ is fixed

Geometric dynamics of HO

from the shear group

Similarly, the Hamiltonian of HO for the shear group ($x_2 \neq 0$) is

$$\begin{aligned} H &= \left(\frac{1}{2m}(\text{id}\tilde{\rho}_{\hbar_4}^{X_1})^2 + \frac{m\omega^2}{2}(\text{id}\tilde{\rho}_{\hbar_4}^{X_3})^2\right) \\ &= -\frac{1}{2m}\partial_{11}^2 - \frac{1}{2m}x_2^2\partial_{33}^2 - \frac{m\omega^2}{2}\partial_{33}^2 - \frac{1}{m}x_2\partial_{13}^2 \\ &\quad + \frac{2\pi i\hbar_4}{m}x_3\partial_1 + \frac{2\pi i\hbar_4}{m}x_2x_3\partial_3 - \frac{1}{m}(-\pi i\hbar_4x_2 - 2\pi^2\hbar_4^2x_3^2)I \end{aligned} \quad (28)$$

Adjusting by the analytic (25) and structural (22) conditions:

$$H_1 = H + (A\partial_1 + B\partial_2 + C\partial_3 + KI)\mathcal{C} + FS.$$

To eliminate all second order derivatives take $A = \frac{1}{2m}$, $B = 0$,
 $C = \frac{1}{m}(\frac{i}{2}E + x_2)$, $K = \frac{\pi\hbar_4}{m}x_1(E + 2ix_2)$. and $F = -\frac{1}{2m}(ix_2 - E)^2 + \frac{m\omega^2}{2}$.

Difference with the Heisenberg group: there is no restrictions for the parameter E , any squeezed states²⁰⁻²¹ $e^{\pi\hbar_4 E y^2}$, $E < 0$ can be mother wavelet.

²⁰Gazeau, *Coherent States in Quantum Physics*, 2009.

²¹M. A. d. Gosson, *Symplectic Methods in Harmonic Analysis and in Mathematical Physics*, 2011; M. A. d. Gosson, "Quantum Blobs", 2013.

Geometric dynamics of HO on the shear group solution

The adjusted Hamiltonian is:

$$H_1 = \frac{2\pi i \hbar_4}{m} \left((x_3 + x_1 x_2) \partial_1 - ((ix_2 - E)^2 - m^2 \omega^2) \partial_2 - (E^2 x_1 - x_2 x_3) \partial_3 \right) \\ - \frac{\pi \hbar_4}{m} \left(8i\pi \hbar_2 E x_2 - ix_2 + 4\pi \hbar_2 x_2^2 - 2\pi \hbar_4 x_3^2 \right. \\ \left. + 4\pi \hbar_2 m^2 \omega^2 + E - 4\pi \hbar_2 E^2 + 4i\pi E \hbar_4 x_1^2 x_2 + 2\pi \hbar_4 E^2 x_1^2 \right) I.$$

Using the analyticity condition in the variable $z = x_3 + iEx_1$:

$$f(t, x_1, x_2, x_3) = \frac{\sqrt{E + m\omega}}{\sqrt{ix_2 + E + m\omega}} \quad (29) \\ \times \exp \left(i\pi\omega t - \pi \hbar_4 E x_1^2 - 2\pi i \hbar_2 x_2 - \pi \hbar_4 \frac{(x_3 - iEx_1)^2}{ix_2 + E + m\omega} \right) \\ \times f_1 \left(e^{2\pi i \omega t} \frac{x_3 - iEx_1}{ix_2 + E + m\omega}, e^{4\pi i \omega t} \frac{m\omega - (ix_2 + E)}{m\omega + (ix_2 + E)} \right).$$

where $f_1(z, u)$ is an arbitrary function of two variables such that:

▶ analytic in the first variable.

▶ solves heat-like eqn. $\partial_u f_1(z, u) = -\frac{1}{8\pi \hbar_4 m \omega} \partial_{zz}^2 f_1(z, u)$

The solution: bounds for a possible squeeze

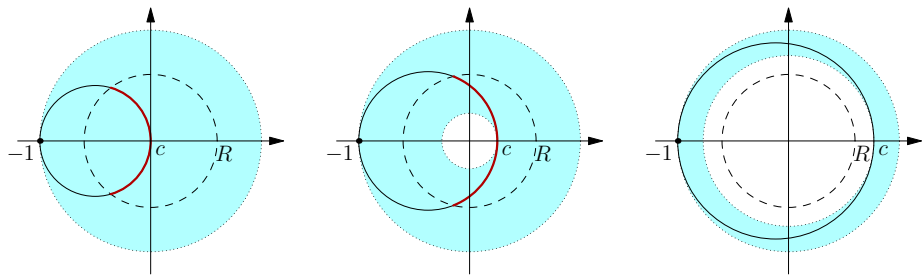


Figure: Shear parameter and analytic continuation. The solid circle is the image of the line $ix_2 + E$ under the Cayley transformation. The shadowed region (the annulus with radii c and 1) is obtained from the solid circle under rotation around the origin. The dashed circle of the radius R bounds the domain of the analytic continuation of the heat equation solution.

Left: $E = m\omega$ (thus $c = 0$)—there always exists a part of the shaded region inside the circle of a radius R (even for $R = 0$).

Middle: some E within the bound—there is a thick arc inside of the dashed circle, the arc corresponds to values of x_2 with a meaningful solution (29).

Right: a shear parameter E is outside of the range, a state is squeezed too much, no values of x_2 are allowed in (29).

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